AD VIK Plant : P14		TPM CIRCLE NO :- 1		ACTIVITY	KK	KK QM		JH	SHE OTPM		DM E&T				
		TPM CIRCLE NAME :		LOSS NO./STEP		Q	P	P, C						ZEN IDEA HEET	
		DEPT :	ME	RESULT AREA	С				S	M, D	P, C	М			
CELL	A467	CELL NAME: Tensioner Assembly M/C STAGE: Er						gravin	g	OPER	OPERATION:				
	KAIZEN THEME :		KAIZEN IDEA:												
To eliminate Hand intervention		Make Spring loading elements for Component holding							BENCHMARK:						
		COUNTERMEASURE:								TARGET: 24.10.18					
PR	OBLEM PRESENT STATUS :									TARGET DATE: 26.10					
	e code marking operator holding	To made Spring loaded Ball plunger type elements to avoid operator hand							KAIZEN FINISH: 26.10						
	ally and There is no Proper	intervention and proper clamping							TEAM MEMBERS:						
Γ	to avoid vibration	intervention and proper clamping							Mr. Mallikarjuna N						
Ciamping	to avoid vibration									Mr. Madhukara D C					
							BENEFITS:- Avoid rejection & tools damage								
									Avoid	l rejec	tion &	tools	lamage		
WHY-WHY ANALYSIS:		BEFORE			AFTER				KAIZEN SUSTAINANCE						
<b>Why1:</b> - No	umber Mismatch and not clearly							WHAT TO DO:							
visible									HOW TO DO: Manual						
 <b>Why2:-</b> Wl	hen date code marking operator	157						1	FREQ	UENC	Y: One	e time .	Activity		
holing job his hand and it my disturb or									SCOPE & PLAN FOR HORIZONTAL						
vibrate	ŕ								DEPLOYMENT						
<b>Why3:</b> -Th avoid vibi	nere is no Proper clamping to ration								SR. NO.	LL/ PROC	DUCT '	TDC	RESP.	STATUS	
	ROOT CAUSE	RESULTS:		\		_	_		1	-		-			
There is n	o Proper clamping to avoid	➤ Quality produ	ct												
vibration															
		Productivity improved							HD SCOPE INFORMATION IN OTHER PLANT						
REGISTRATION NO.: P14/KK/2018/11		> Zero Accident													
DATE		†							SR.NO	. PLA	NT W	/HEN	wном	STATUS	
REGISTER									1						
MANAGE	R SIGN: Mr.Praveen Jannu														
IVIAIVAGE	N SIGIA.														