		TPM CIRCLE NO :-			ACTIVITY	KK	QM	PM JH	SHE	OT	DM	E&T				
ADV IK		TPM CIRCLE NAME :- DEPT :-			LOSS NO. / STEP											JCCT
					RESULT AREA	P Q		DEF :- A / B / C		D			KAIZEN IDEA SHEET			1661
CELL :- 02	CELL	NAME:-BCOF	MAC	CHINE / STAGE :- Balancing OPERATION :-Balancing												
KAIZEN THEME Sensor dama		duce possibi	ity of		:- Sensor covered.	wide	tha		over	E	BENCH	MARK		Possibili	ty of d	lamage
WIDELY/DEEPLY:-			COUNTERMEASURE:- Provide the pipe cover on proximity sensor so that no chance for							TARGETReduce possibility of cKAIZEN START14.9.2016					ity of da	
PROBLEM / PRESENT STATUS :- During operating balancing machine chance of sensor damage.				dar	nage possibility.	1 11		-		H T F	K <mark>AIZEN</mark> TEAM N Rajesł	I FINISH /IEMBEH	H RS :- Iar, Par	19.9.2 meshwar	016	ma
Sensor not Cover BEFORE			(Sensor Covered AFTER						BENEFITS :- Operator moral increase Sensor life increase.						
										KAIZEN SUSTENANCE						
WHY-WHY ANALYSIS :-					RESULT :-Reduce possibility of sensor damage.						WHAT TO DO :-Check point add in JH					
WHY 1:- Chance of Sensor Damage Why 2 :- Operator may be hit the part on			Possibility of						ł	HOW TO DO :- Visual						
Sensor. WHY 3:- Sensor	not cov	/er.		Damage Sensor Reduce						F	FREQUENCY :-Monthly					
					ຍ		Possibility of sensor			CO	ST INCI	JRRED FOR MAKING KAIZEN				
					Occurrence			damage			MATERIAL COST RS.				AL COST RS.	
ROOT CAUSE :- Se	OOT CAUSE :- Sensor not cover.				Ū O											
REGISTRATION NO&DATE:			-	r					SF	SR		AN FOR HORIZONTAL DEP				
REGISTERED BY :-					Before			After		N	o. Ci		TARGET	KESPONSIB	ILIIY	STATU
				7							N	A				